74AUP1Z04Low-power X-tal driver with enable and internal resistorRev. 5 - 9 August 2012Product data sheet

1. General description

The 74AUP1Z04 combines the functions of the 74AUP1GU04 and 74AUP1G04 with enable circuitry and an internal bias resistor to provide a device optimized for use in crystal oscillator applications.

When not in use the $\overline{\text{EN}}$ input can be driven HIGH, putting the device in a low power disable mode with X1 pulled HIGH via R_{PU}, X2 set LOW and Y set HIGH.Schmitt trigger action at the $\overline{\text{EN}}$ input makes the circuit tolerant to slower input rise and fall times across the entire V_{CC} range from 0.8 V to 3.6 V.

This device is fully specified for partial power-down applications using I_{OFF} at output Y. The I_{OFF} circuitry disables the output Y, preventing the damaging backflow current through the device when it is powered down.

The integration of the two devices into the 74AUP1Z04 produces the benefits of a compact footprint, lower power dissipation and stable operation over a wide range of frequency and temperature.

2. Features and benefits

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- ESD protection:
 - HBM JESD22-A114F Class 3A exceeds 5000 V
 - MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101E exceeds 1000 V
- Latch-up performance exceeds 100 mA per JESD78B Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot < 10 % of V_{CC}
- I_{OFF} circuitry provides partial Power-down mode operation at output Y
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



Low-power X-tal driver with enable and internal resistor

3. Ordering information

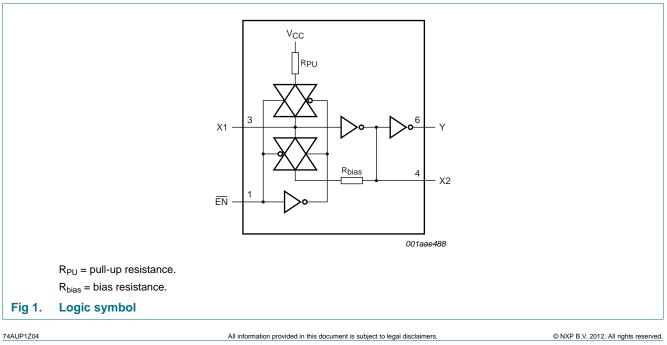
Table 1. Ordering	g information							
Type number	Package							
	Temperature range Name		Description	Version				
74AUP1Z04GW	–40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363				
74AUP1Z04GM	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 \times 1.45 \times 0.5 mm	SOT886				
74AUP1Z04GF	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 \times 1 \times 0.5 mm	SOT891				
74AUP1Z04GN	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $0.9 \times 1.0 \times 0.35$ mm	SOT1115				
74AUP1Z04GS	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $1.0 \times 1.0 \times 0.35$ mm	SOT1202				

4. Marking

Table 2. Marking	
Type number	Marking code ^[1]
74AUP1Z04GW	a4
74AUP1Z04GM	a4
74AUP1Z04GF	a4
74AUP1Z04GN	a4
74AUP1Z04GS	a4

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

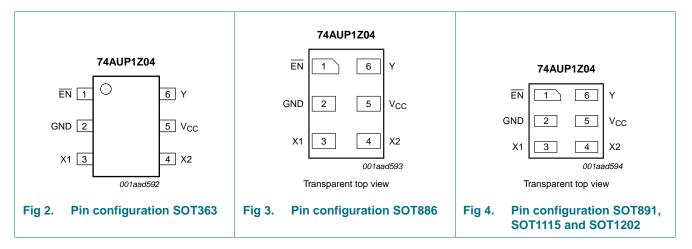
5. Functional diagram



Low-power X-tal driver with enable and internal resistor

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3.	Pin description	
Symbol	Pin	Description
EN	1	enable input (active LOW)
GND	2	ground (0 V)
X1	3	data input
X2	4	data output
V _{CC}	5	supply voltage
Y	6	data output

7. Functional description

Table 4.Function table^[1]

Input C		Output		
EN	X1	X2	Y	
L	L	Н	L	
L	Н	L	Н	
Н	L	Н	L	
Н	Н	L	Н	

[1] H = HIGH voltage level; L = LOW voltage level.

Low-power X-tal driver with enable and internal resistor

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

					,
Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	supply voltage		-0.5	+4.6	V
l _{IK}	input clamping current	V _I < 0 V	-50	-	mA
VI	input voltage		<u>[1]</u> –0.5	+4.6	V
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Vo	output voltage		<u>[1]</u> –0.5	V _{CC} + 0.5	V
lo	output current	$V_{O} = 0 V$ to V_{CC}	-	±20	mA
I _{CC}	supply current		-	50	mA
I _{GND}	ground current		-50	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	$T_{amb} = -40 \ ^{\circ}C$ to +125 $^{\circ}C$	[2] _	250	mW

[1] The minimum input and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] For SC-88 packages: above 87.5 °C the value of P_{tot} derates linearly with 4.0 mW/K. For XSON6 packages: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K.

9. Recommended operating conditions

Table 0.	Recommended operating conditi	0115			
Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	supply voltage		0.8	3.6	V
VI	input voltage		0	3.6	V
Vo	output voltage		0	V_{CC}	V
T _{amb}	ambient temperature		-40	+125	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{CC} = 0.8 V$ to 3.6 V	-	200	ns/V

Table 6. Recommended operating conditions

Low-power X-tal driver with enable and internal resistor

10. Static characteristics

Table 7. Static characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
T _{amb} = 2	5 °C					
Ин	HIGH-level input voltage	X1 input				
		V_{CC} = 0.8 V to 3.6 V	$0.75 \times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 V$	$0.70\times V_{CC}$	-	-	V
		$V_{CC} = 0.9 V$ to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		V_{CC} = 2.3 V to 2.7 V	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.0	-	-	V
′IL	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 V$ to 3.6 V	-	-	$0.25\times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 V$	-	-	$0.30\times V_{CC}$	V
		$V_{CC} = 0.9 V$ to 1.95 V	-	-	$0.35\times V_{CC}$	V
		V_{CC} = 2.3 V to 2.7 V	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	-	-	0.9	V
V _{OH}	HIGH-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_{O} = -20 μ A; V_{CC} = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75\times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.6	-	-	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_{O} = -20 μ A; V _{CC} = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_0 = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_0 = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_0 = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_0 = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_0 = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_0 = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.6	-	-	V

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
√ _{OL}	LOW-level output voltage	Y output; V _I at X1 input = V _{IH} or V _{IL}				
		I_{O} = 20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3\times V_{CC}$	V
		$I_{O} = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	- 0.31	0.31	V
		$I_0 = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.31	V
		$I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_0 = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
		X2 output; $V_1 = GND$ or V_{CC}				
		I_{O} = 20 μ A; V_{CC} = 0.8 V to 3.6 V	-	-	0.1	V
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	$0.3 \times V_{CC}$	V
		$I_0 = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		I _O = 1.9 mA; V _{CC} = 1.65 V	-	-	0.31	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.31	V
		$I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_0 = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_{O} = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
I	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$; $V_{CC} = 0 V$ to 3.6 V	-	-	±0.1	μA
		EN input				
		V _I = GND to 3.6 V; V _{CC} = 0 V to 3.6 V	-	-	±0.1	μΑ
pu	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$	-	-	15	μA
OFF	power-off leakage current	V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V	<u>[1]</u> _	-	±0.2	μA
∆l _{OFF}	additional power-off leakage current	$V_1 \text{ or } V_0 = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 0.2 \text{ V}$	<u>[1]</u> -	-	±0.2	μΑ
СС	supply current	$\label{eq:V_l} \begin{array}{l} V_l = GND \text{ or } V_{CC}; \ I_O = 0 \text{ A}; \\ \overline{EN} = GND; \ V_{CC} = 0.8 \text{ V to } 3.6 \text{ V} \end{array}$	-	-	75	μA
کا _{CC}	additional supply current	EN input				
			-	-	40	μA
C _I	input capacitance	X1 input				
		$V_{CC} = 0 V$ to 3.6 V; V _I = GND or V _{CC}	-	1.3	-	pF
		EN input				
		$V_{CC} = 0 V$ to 3.6 V; V _I = GND or V _{CC}	-	0.8	-	pF

6 of 28

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Co	output capacitance	X2 output				
		$V_O = GND; V_{CC} = 0 V$	-	1.5	-	pF
		Y output				
		$V_O = GND; V_{CC} = 0 V$	-	1.7	-	pF
g fs	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 V$	-	-	-	mA/V
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	0.2	-	9.9	mA/V
		$V_{CC} = 1.4 \text{ V} \text{ to } 1.6 \text{ V}$	3.9	-	17.7	mA/V
		$V_{CC} = 1.65 \text{ V} \text{ to } 1.95 \text{ V}$	7.9	-	24.3	mA/V
		V_{CC} = 2.3 V to 2.7 V	18	-	30.7	mA/V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	20.5	-	32.4	mA/V
R _{bias}	bias resistance	$\overline{EN} = GND; f_i = 0 Hz; V_1 = 0 V or V_{CC}; see Figure 5; for frequency behavior see Figure 6$	1.08	1.62	3.08	MΩ
T _{amb} = –	40 °C to +85 °C					
VIH	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 V$ to 3.6 V	$0.75\times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 V$	$0.70\times V_{CC}$	-	-	V
		$V_{CC} = 0.9 V$ to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		V_{CC} = 2.3 V to 2.7 V	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	2.0	-	-	V
V _{IL}	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 V \text{ to } 3.6 V$	-	-	$0.25\times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 V$	-	-	$0.30 \times V_{CC}$	V
		$V_{CC} = 0.9 V$ to 1.95 V	-	-	$0.35 \times V_{CC}$	V
		$V_{CC} = 2.3 \text{ V} \text{ to } 2.7 \text{ V}$	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$	-	-	0.9	V

Table 7. Static characteristics ... continued

74AUP1Z04 Product data sheet

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

Symbol	Parameter	Conditions	Min	Тур	Max	Uni
V _{OH}	HIGH-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				
		I_O = $-20~\mu\text{A};~V_{CC}$ = 0.8 V to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7\times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		I_{O} = -1.9 mA; V_{CC} = 1.65 V	1.30	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.97	-	-	V
		I_{O} = -3.1 mA; V_{CC} = 2.3 V	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		I_{O} = -4.0 mA; V_{CC} = 3.0 V	2.55	-	-	V
		V_{I} at X1 input = V_{IH} or V_{IL}				
		I_O = –20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	$V_{CC} - 0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7\times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.97	-	-	V
		I_{O} = -3.1 mA; V_{CC} = 2.3 V	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		I_{O} = -4.0 mA; V_{CC} = 3.0 V	2.55	-	-	V
V _{OL}	LOW-level output voltage	Y output; V_I at X1 input = V_{IH} or V_{IL}				
		I_O = 20 $\mu A;V_{CC}$ = 0.8 V to 3.6 V	-	-	0.1	V
		I_{O} = 1.1 mA; V_{CC} = 1.1 V	-	-	$0.3\times V_{CC}$	V
		I_{O} = 1.7 mA; V_{CC} = 1.4 V	-	-	0.37	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.35	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.33	V
		I_{O} = 3.1 mA; V_{CC} = 2.3 V	-	-	0.45	V
		I_{O} = 2.7 mA; V_{CC} = 3.0 V	-	-	0.33	V
		I_{O} = 4.0 mA; V_{CC} = 3.0 V	-	-	0.45	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_O = 20 $\mu A;V_{CC}$ = 0.8 V to 3.6 V	-	-	0.1	V
		I_{O} = 1.1 mA; V_{CC} = 1.1 V	-	-	$0.3\times V_{CC}$	V
		I_{O} = 1.7 mA; V_{CC} = 1.4 V	-	-	0.37	V
		I_{O} = 1.9 mA; V_{CC} = 1.65 V	-	-	0.35	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.33	V
		I_{O} = 3.1 mA; V_{CC} = 2.3 V	-	-	0.45	V
		I_{O} = 2.7 mA; V_{CC} = 3.0 V	-	-	0.33	V
		$I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.45	V

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
li -	input leakage current	X1 input					
		$V_I = \overline{EN} = V_{CC}$; $V_{CC} = 0$ V to 3.6 V		-	-	±0.5	μΑ
		EN input					
		V _I = GND to 3.6 V; V _{CC} = 0 V to 3.6 V	,	-	-	±0.5	μA
l _{pu}	pull-up current	X1 input; $\overline{EN} = V_{CC}$					
		$V_{I} = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$		-	-	15	μΑ
I _{OFF}	power-off leakage current	$V_{\rm I}~{\rm or}~V_{\rm O}$ = 0 V to 3.6 V; $V_{\rm CC}$ = 0 V	[1]	-	-	±0.5	μA
ΔI_{OFF}	additional power-off leakage current	$ V_{I} \text{ or } V_{O} = 0 \text{ V to } 3.6 \text{ V}; $	<u>[1]</u>	-	-	±0.6	μΑ
I _{CC}	supply current	$\frac{V_{I} = \text{GND or } V_{CC}; I_{O} = 0 \text{ A};}{\overline{\text{EN}} = \text{GND}; V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}}$,	-	-	75	μA
∆l _{CC}	additional supply current	EN input					
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$,	-	-	50	μΑ
g _{fs}	forward transconductance	see Figure 10 and Figure 11					
		$V_{CC} = 0.8 V$		-	-	-	mA/\
		$V_{CC} = 1.1 \text{ V} \text{ to } 1.3 \text{ V}$		-	-	10.8	mA/
		$V_{CC} = 1.4 \text{ V}$ to 1.6 V		1.8	-	21.2	mA/\
		$V_{CC} = 1.65 \text{ V}$ to 1.95 V		7.5	-	29.9	mA/\
		V_{CC} = 2.3 V to 2.7 V		15.0	-	38.0	mA/\
		V_{CC} = 3.0 V to 3.6 V		17.8	-	39.2	mA/\
R _{bias}	bias resistance	$\overline{EN} = GND; f_i = 0 Hz; V_l = 0 V or V_{CC}; see Figure 5; for frequency behavior see Figure 6$		1.07	-	3.11	MΩ
T _{amb} = –	40 °C to +125 °C						
V _{IH}	HIGH-level input voltage	X1 input					
		$V_{CC} = 0.8 V \text{ to } 3.6 V$		$0.75 \times V_{CC}$	-	-	V
		EN input					
		$V_{CC} = 0.8 V$		$0.75 \times V_{CC}$	-	-	V
		$V_{CC} = 0.9 V$ to 1.95 V		$0.70 \times V_{CC}$	-	-	V
		$V_{CC} = 2.3 \text{ V} \text{ to } 2.7 \text{ V}$		1.6	-	-	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$		2.0	-	-	V
VIL	LOW-level input voltage	X1 input					
		$V_{CC} = 0.8 V \text{ to } 3.6 V$		-	-	$0.25 \times V_{CC}$	V
		EN input					
		$V_{CC} = 0.8 V$		-	-	$0.25\times V_{CC}$	V
		V_{CC} = 0.9 V to 1.95 V		-	-	$0.30\times V_{CC}$	V
		V_{CC} = 2.3 V to 2.7 V		-	-	0.7	V
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$		-	-	0.9	V

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

Table 7. Static characteristics ...continued

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
∕ _{он}	HIGH-level output voltage	Y output; V _I at X1 input = V_{IH} or V_{IL}				V
		I_O = $-20~\mu\text{A};~V_{CC}$ = 0.8 V to 3.6 V	V _{CC} - 0.11	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6\times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		I_{O} = -1.9 mA; V_{CC} = 1.65 V	1.17	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.77	-	-	V
		I_{O} = -3.1 mA; V_{CC} = 2.3 V	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		I_{O} = -4.0 mA; V_{CC} = 3.0 V	2.30	-	-	V
		X2 output; $V_I = GND$ or V_{CC}				V
		I_{O} = –20 $\mu\text{A};V_{CC}$ = 0.8 V to 3.6 V	V _{CC} - 0.11	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		I_{O} = -2.3 mA; V_{CC} = 2.3 V	1.77	-	-	V
		I_{O} = -3.1 mA; V_{CC} = 2.3 V	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		I_{O} = -4.0 mA; V_{CC} = 3.0 V	2.30	-	-	V
OL	LOW-level output voltage	Y output; V_I at X1 input = V_{IH} or V_{IL}				
		I_O = 20 μ A; V_{CC} = 0.8 V to 3.6 V	-	-	0.11	V
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		I_{O} = 1.7 mA; V_{CC} = 1.4 V	-	-	0.41	V
		I _O = 1.9 mA; V _{CC} = 1.65 V	-	-	0.39	V
		I_{O} = 2.3 mA; V_{CC} = 2.3 V	-	-	0.36	V
		I_{O} = 3.1 mA; V_{CC} = 2.3 V	-	-	0.50	V
		I_{O} = 2.7 mA; V_{CC} = 3.0 V	-	-	0.36	V
		I_{O} = 4.0 mA; V_{CC} = 3.0 V	-	-	0.50	V
		X2 output; $V_I = GND$ or V_{CC}				
		I_O = 20 μ A; V_{CC} = 0.8 V to 3.6 V	-	-	0.11	V
		I _O = 1.1 mA; V _{CC} = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		I_0 = 1.7 mA; V_{CC} = 1.4 V	-	-	0.41	V
		I _O = 1.9 mA; V _{CC} = 1.65 V	-	-	0.39	V
		I_0 = 2.3 mA; V_{CC} = 2.3 V	-	-	0.36	V
		I _O = 3.1 mA; V _{CC} = 2.3 V	-	-	0.50	V
		$I_0 = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.36	V
		$I_0 = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.50	V

74AUP1Z04

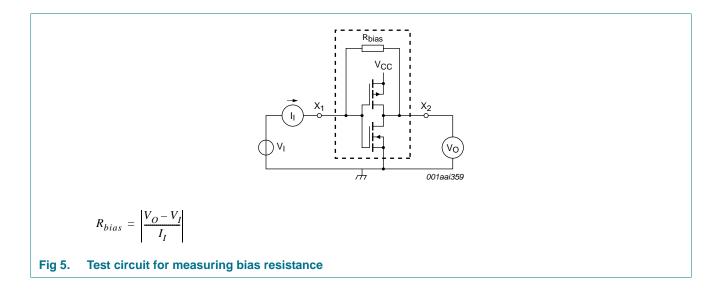
Low-power X-tal driver with enable and internal resistor

Symbol Parameter Conditions Min Тур Max Unit input leakage current X1 input I_L $V_I = \overline{EN} = V_{CC}$; $V_{CC} = 0$ V to 3.6 V ±0.75 -μΑ EN input $V_I = GND$ to 3.6 V; μΑ ±0.75 - $V_{CC} = 0 V \text{ to } 3.6 V$ X1 input; $\overline{EN} = V_{CC}$ pull-up current I_{pu} $V_{I} = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$ 15 μA -[1] _ power-off leakage current V_{I} or $V_{O} = 0$ V to 3.6 V; $V_{CC} = 0$ V ±0.75 μΑ **I**OFF -[1] _ additional power-off V_{I} or $V_{O} = 0$ V to 3.6 V; ± 0.75 ΔI_{OFF} μΑ $V_{CC} = 0 V \text{ to } 0.2 V$ leakage current $V_I = GND \text{ or } V_{CC}; I_O = 0 \text{ A};$ 75 Icc supply current μΑ _ $\overline{EN} = GND; V_{CC} = 0.8 V \text{ to } 3.6 V$ additional supply current **EN** input ΔI_{CC} $V_{I} = V_{CC} - 0.6 V; I_{O} = 0 A;$ 75 -_ μΑ $V_{CC} = 3.3 V$ see Figure 10 and Figure 11 forward transconductance g_{fs} $V_{CC} = 0.8 V$ mA/V --- $V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$ -10.8 mA/V _ $V_{CC} = 1.4 \text{ V}$ to 1.6 V 21.2 mA/V 1.8 - $V_{CC} = 1.65 \text{ V}$ to 1.95 V 6.9 29.9 mA/V - $V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$ 13.4 38.0 mA/V - $V_{CC} = 3.0 V \text{ to } 3.6 V$ mA/V 15.8 39.2 _ bias resistance $\overline{\text{EN}} = \text{GND}$; $f_i = 0$ Hz; $V_i = 0$ V or 1.07 3.11 MΩ **R**_{bias} V_{CC}; see Figure 5; for frequency behavior see Figure 6

Static characteristics ... continued Table 7.

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

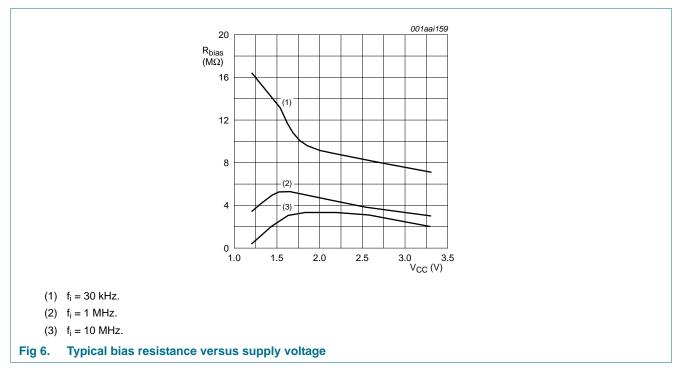
[1] Only for output Y and input \overline{EN} .



11 of 28

74AUP1Z04

Low-power X-tal driver with enable and internal resistor



11. Dynamic characteristics

Table 8.Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol	Parameter	Conditions	Т	amb =25	°C	T _{amb} =	–40 °C to	• +125 ℃	Unit
			Min	Typ <mark>[1]</mark>	Max	Min	Max (85 °C)	Max (125 °C)	
C _L = 5 pl	F								
t _{pd}	propagation delay	X1 to X2; see Figure 7	2]						
		$V_{CC} = 0.8 V$	-	12.8	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V}$ to 1.3 V	1.2	3.0	3.9	1.2	3.9	3.9	ns
		V_{CC} = 1.4 V to 1.6 V	1.0	2.2	2.6	1.0	2.7	2.7	ns
		V_{CC} = 1.65 V to 1.95 V	0.8	1.9	2.3	0.8	2.4	2.5	ns
		V_{CC} = 2.3 V to 2.7 V	0.7	1.6	1.9	0.7	2.0	2.0	ns
		V_{CC} = 3.0 V to 3.6 V	0.7	1.4	1.6	0.7	1.7	1.7	ns
		X1 to Y; see Figure 8	2]						
		V _{CC} = 0.8 V	-	39.2	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V} \text{ to } 1.3 \text{ V}$	2.5	8.0	10.7	2.3	10.8	10.9	ns
		V_{CC} = 1.4 V to 1.6 V	2.2	5.5	6.6	2.0	7.0	7.0	ns
		V_{CC} = 1.65 V to 1.95 V	1.8	4.4	5.5	1.7	5.9	6.0	ns
		V_{CC} = 2.3 V to 2.7 V	1.5	3.5	4.1	1.4	4.4	4.5	ns
		$V_{CC} = 3.0 V \text{ to } 3.6 V$	1.5	3.1	3.5	1.4	3.8	3.8	ns

Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions	٢	amb =25	°C	T _{amb} =	–40 °C to	o +125 °C	Unit
			Min	Typ <mark>[1]</mark>	Max	Min Max (85 °C)		Max (125 °C)	
C _L = 10	ρF		1						
t _{pd}	propagation delay	X1 to X2; see Figure 7	1						
		$V_{CC} = 0.8 V$	-	20.9	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V} \text{ to } 1.3 \text{ V}$	1.4	4.1	5.4	1.3	5.6	5.6	ns
		$V_{CC} = 1.4 \text{ V} \text{ to } 1.6 \text{ V}$	1.3	2.9	3.6	1.2	3.8	3.8	ns
		V_{CC} = 1.65 V to 1.95 V	1.2	2.5	3.0	1.1	3.2	3.2	ns
		V_{CC} = 2.3 V to 2.7 V	0.9	2.0	2.4	0.8	2.5	2.5	ns
		V_{CC} = 3.0 V to 3.6 V	0.9	1.8	2.1	0.8	2.3	2.3	ns
		X1 to Y; see Figure 8	1						
		$V_{CC} = 0.8 V$	-	46.6	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	2.7	9.2	12.4	2.5	12.7	12.7	ns
		X1 to Y; see Figure 8 [2] $V_{CC} = 0.8 V$ - 46.6 - $V_{CC} = 1.1 V$ to $1.3 V$ 2.7 9.2 12.4 $V_{CC} = 1.4 V$ to $1.6 V$ 2.5 6.3 7.8 $V_{CC} = 1.65 V$ to $1.95 V$ 2.3 5.0 6.2 $V_{CC} = 2.3 V$ to $2.7 V$ 1.8 4.0 4.7 $V_{CC} = 3.0 V$ to $3.6 V$ 1.9 3.6 4.2	2.2	8.2	8.2	ns			
		V_{CC} = 1.65 V to 1.95 V	2.3	5.0	6.2	2.2	6.7	6.7	ns
		V_{CC} = 2.3 V to 2.7 V	1.8	4.0	4.7	1.7	5.0	5.1	ns
		V_{CC} = 3.0 V to 3.6 V	1.9	3.6	4.2	1.8	4.5	4.5	ns
C _L = 15	ρF								
t _{pd}	propagation delay	X1 to X2; see Figure 7	1						
		$V_{CC} = 0.8 V$	-	28.9	-	-	-	-	ns
		$V_{CC} = 1.1 V \text{ to } 1.3 V$	1.7	5.2	7.1	1.6	7.2	7.3	ns
		V_{CC} = 1.4 V to 1.6 V	1.6	3.6	4.4	1.6	4.7	4.8	ns
		V_{CC} = 1.65 V to 1.95 V	$_{\rm C} = 1.4$ V to 1.6 V1.63.6 $_{\rm C} = 1.65$ V to 1.95 V1.33.0		3.7	1.3	3.9	4.0	ns
		V_{CC} = 2.3 V to 2.7 V	1.0	2.4	12.4 2.5 12.7 12.7 12.7 7.8 2.2 8.2 8.2 8.2 6.2 2.2 6.7 6.7 6.7 4.7 1.7 5.0 5.1 6.7 4.2 1.8 4.5 4.5 6.7 7.1 1.6 7.2 7.3 6.7 4.4 1.6 4.7 4.8 6.7 3.7 1.3 3.9 4.0 6.7 2.9 1.0 3.1 3.1 6.7 2.5 1.0 2.7 2.7 6.7 4.4 2.8 14.6 14.7 6.7 4.4 1.6 2.7 2.7 6.7 4.4 1.6 4.7 4.8 6.7 4.4 1.6 4.7 4.8 6.7 4.4 1.6 4.7 6.7 6.7 4.4 1.6 4.7 6.7 6.7 4.8 $7.$	ns			
		V_{CC} = 3.0 V to 3.6 V	1.1	2.2	2.5	1.0	2.7	2.7	ns
		X1 to Y; see Figure 8	1						
		$V_{CC} = 0.8 V$	-	53.9	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V	3.1	10.4	14.2	2.8	14.6	14.7	ns
		$V_{CC} = 1.4 \text{ V}$ to 1.6 V	2.9	7.0	8.5	2.7	9.2	9.3	ns
		V_{CC} = 1.65 V to 1.95 V	2.5	5.6	6.9	2.3	7.4	7.5	ns
		V_{CC} = 2.3 V to 2.7 V	2.1	4.5	5.4	2.0	5.7	5.7	ns
		V_{CC} = 3.0 V to 3.6 V	2.3	4.1	4.7	2.1	5.1	5.1	ns

Table 8. Dynamic characteristics ... continued Voltages are referenced to GND (ground = 0 V): for test circuit see Figure 9.

Low-power X-tal driver with enable and internal resistor

Symbol	Parameter	Conditions		T,	_{amb} =25 °	°C	T _{amb} =	–40 °C to	• +125 °C	Uni
				Min	Typ <mark>[1]</mark>	Мах	Min	Max (85 °C)	Max (125 °C)	
C _L = 30	pF									
t _{pd} propagation delay		X1 to X2; see Figure 7	[2]							
		$V_{CC} = 0.8 V$		-	52.8	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V		2.4	8.5	11.8	2.3	12.2	12.4	ns
		$V_{CC} = 1.4 \text{ V} \text{ to } 1.6 \text{ V}$		2.2	5.6	6.8	2.0	7.5	7.6	ns
		V _{CC} = 1.65 V to 1.95 V		2.0	4.5	5.6	1.9	6.2	6.2	ns
		V_{CC} = 2.3 V to 2.7 V		1.5	3.7	4.2	1.4	4.6	4.6	ns
		V_{CC} = 3.0 V to 3.6 V		1.7	3.3	3.7	1.6	4.0	4.2	ns
		X1 to Y; see Figure 8	[2]							
		$V_{CC} = 0.8 V$		-	77.6	-	-	-	-	ns
		V_{CC} = 1.1 V to 1.3 V		3.7	13.8	19.2	3.3	19.8	20.1	ns
		V_{CC} = 1.4 V to 1.6 V		3.4	9.2	11.2	3.1	12.2	12.3	ns
		V_{CC} = 1.65 V to 1.95 V		3.4	7.4	8.8	3.1	9.7	9.7	ns
		V_{CC} = 2.3 V to 2.7 V		2.6	5.9	6.7	2.4	7.4	7.4	ns
		V_{CC} = 3.0 V to 3.6 V		3.2	5.4	6.2	2.9	6.7	6.9	ns
C _L = 5 p	F, 10 pF, 15 pF and	30 pF								
C _{PD}	$\begin{array}{ll} \mbox{power dissipation} & f_i = 1 \mbox{ MHz; } \overline{\mbox{EN}} = \mbox{GND}; \\ \mbox{capacitance} & V_I = \mbox{GND to } V_{CC} \end{array}$		<u>[3][4][5]</u>							
		$V_{CC} = 0.8 V$		-	6.8	-	-	-	-	pF
		V _{CC} = 1.1 V to 1.3 V		-	12.0	-	-	-	-	pF
		V_{CC} = 1.4 V to 1.6 V		-	18.2	-	-	-	-	pF
		V_{CC} = 1.65 V to 1.95 V		-	19.2	-	-	-	-	pF
		V_{CC} = 2.3 V to 2.7 V		-	21.9	-	-	-	-	pF
		$V_{CC} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$		-	24.9	-	-	-	-	pF

Table 8. Dynamic characteristics ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

[1] All typical values are measured at nominal V_{CC} .

[2] t_{pd} is the same as t_{PLH} and t_{PHL} .

[3] All specified values are the average typical values over all stated loads.

[4] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W).

 $P_{D} = C_{PD} \times V_{CC}^{2} \times f_{i} \times N + \Sigma (C_{L} \times V_{CC}^{2} \times f_{o}) \text{ where:}$

 f_i = input frequency in MHz;

 $f_o = output frequency in MHz;$

 C_L = output load capacitance in pF;

 V_{CC} = supply voltage in V;

N = number of inputs switching;

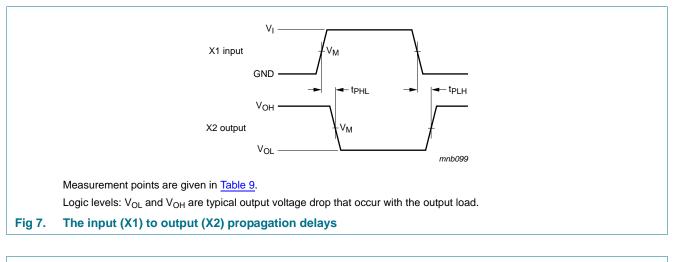
 $\Sigma(C_L \times V_{CC}{}^2 \times f_o)$ = sum of the outputs.

[5] Feedback current is included in the C_{PD} .

14 of 28

Low-power X-tal driver with enable and internal resistor

12. Waveforms



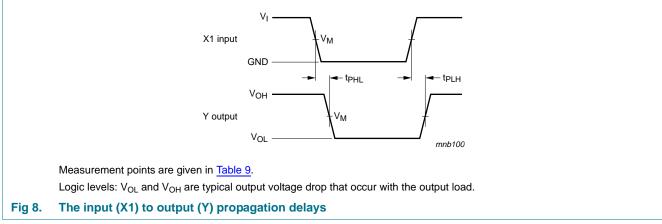


Table 9. Measurement points

Supply voltage	Output	Input		
V _{CC}	V _M	V _M	VI	$t_r = t_f$
0.8 V to 3.6 V	$0.5\times V_{CC}$	$0.5\times V_{CC}$	V _{CC}	≤ 3.0 ns

Low-power X-tal driver with enable and internal resistor

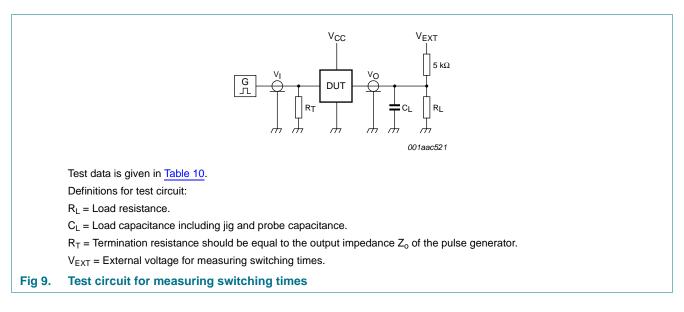
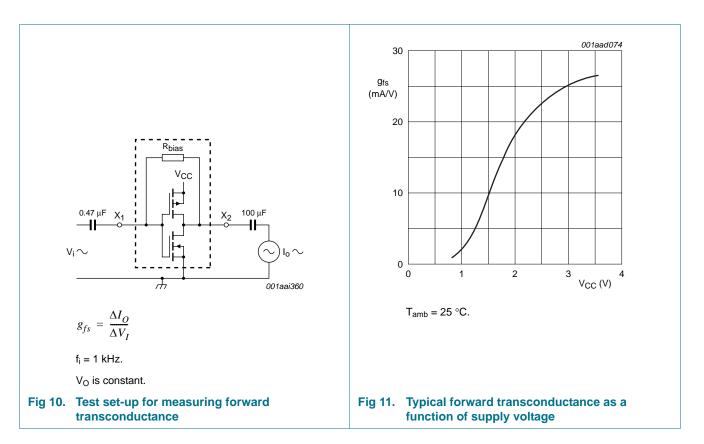


Table 10. Test data

Supply voltage	Load	V _{EXT}			
V _{cc}	CL	R _L [1]	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ}
0.8 V to 3.6 V	5 pF, 10 pF, 15 pF and 30 pF	5 k Ω or 1 M Ω	open	GND	$2 \times V_{CC}$

[1] For measuring enable and disable times $R_L = 5 k\Omega$, for measuring propagation delays, setup and hold times and pulse width $R_L = 1 M\Omega$.

Low-power X-tal driver with enable and internal resistor



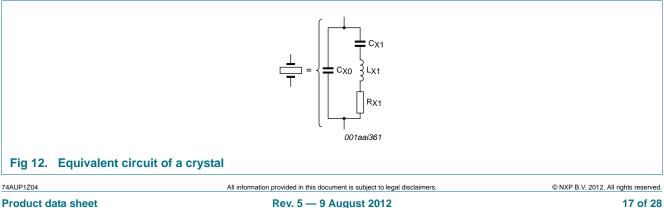
13. Application information

Crystal controlled oscillator circuits are widely used in clock pulse generators because of their excellent frequency stability and wide operating frequency range. The use of the 74AUP1Z04 provides the additional advantages of low power dissipation, stable operation over a wide range of frequency and temperature and a very small footprint. This application information describes crystal characteristics, design and testing of crystal oscillator circuits based on the 74AUP1Z04.

13.1 Crystal characteristics

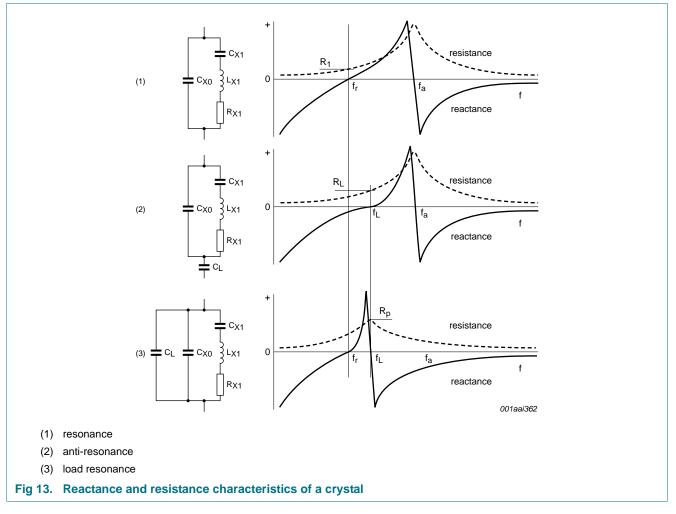
Figure 12 is the equivalent circuit of a quartz crystal.

The reactive and resistive component of the impedance of the crystal alone and the crystal with a series and a parallel capacitance is shown in Figure 13.



74AUP1Z04

Low-power X-tal driver with enable and internal resistor



13.1.1 Design

Figure 14 shows the recommended way to connect a crystal to the 74AUP1Z04. This circuit is basically a Pierce oscillator circuit in which the crystal is operating at its fundamental frequency and is tuned by the parallel load capacitance of C_1 and C_2 . C_1 and C_2 are in series with the crystal. They should be approximately equal. R_1 is the drive-limiting resistor and is set to approximately the same value as the reactance of C_1 at the crystal frequency ($R_1 = X_{C1}$). This will result in an input to the crystal of 50 % of the rail-to-rail output of X2. This keeps the drive level into the crystal within drive specifications (the designer should verify this). Overdriving the crystal can cause damage.

The internal bias resistor provides negative feedback and sets a bias point of the inverter near mid-supply, operating the 74AUP1GU04 portion in the high gain linear region.

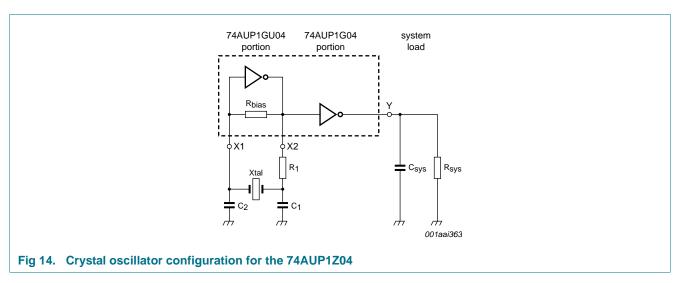
To calculate the values of C_1 and C_2 , the designer can use the formula:

$$C_L = \frac{C_1 \times C_2}{C_1 + C_2} + C_s$$

 C_L is the load capacitance as specified by the crystal manufacturer, C_s is the stray capacitance of the circuit (for the 74AUP1Z04 this is equal to an input capacitance of 1.5 pF).

74AUP1Z04

Low-power X-tal driver with enable and internal resistor



13.1.2 Testing

After the calculations are performed for a particular crystal, the oscillator circuit should be tested. The following simple checks will verify the prototype design of a crystal controlled oscillator circuit. Perform them after laying out the board:

- Test the oscillator over worst-case conditions (lowest supply voltage, worst-case crystal and highest operating temperature). Adding series and parallel resistors can simulate a worst-case crystal.
- Insure that the circuit does not oscillate without the crystal.
- Check the frequency stability over a supply range greater than that which is likely to occur during normal operation.
- Check that the start-up time is within system requirements.

As the 74AUP1Z04 isolates the system loading, once the design is optimized, the single layout may work in multiple applications for any given crystal.

74AUP1Z04

Low-power X-tal driver with enable and internal resistor

14. Package outline

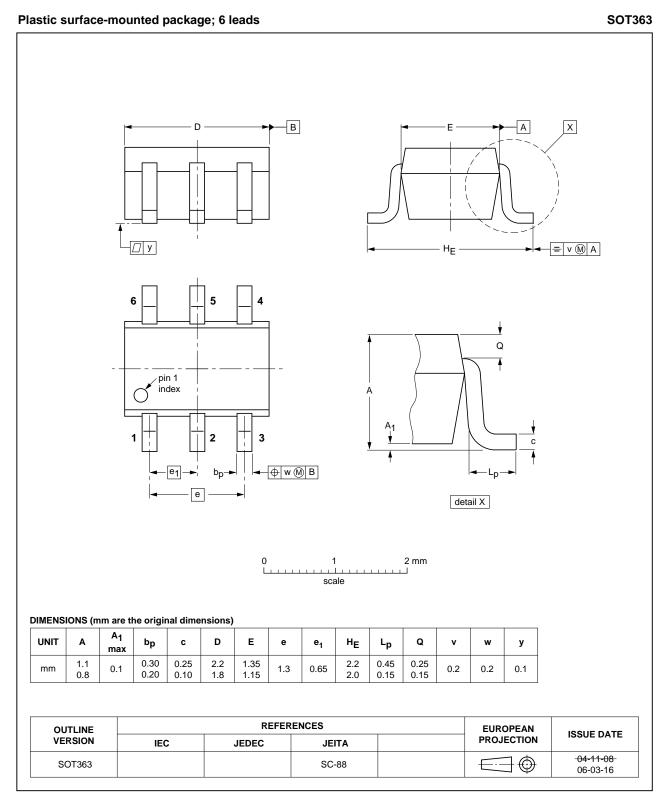


Fig 15. Package outline SOT363 (SC-88)

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74AUP1Z04

Low-power X-tal driver with enable and internal resistor

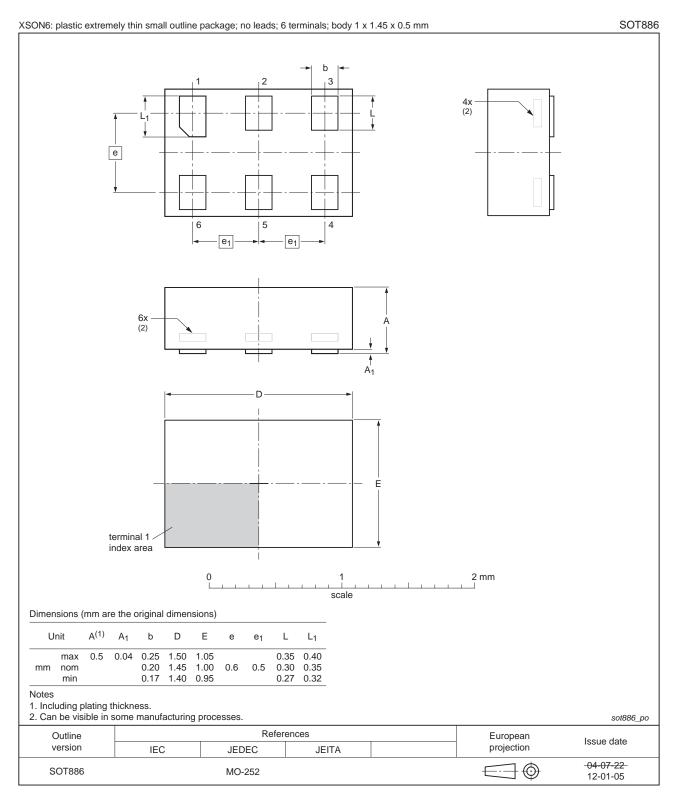


Fig 16. Package outline SOT886 (XSON6)

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74AUP1Z04

Low-power X-tal driver with enable and internal resistor

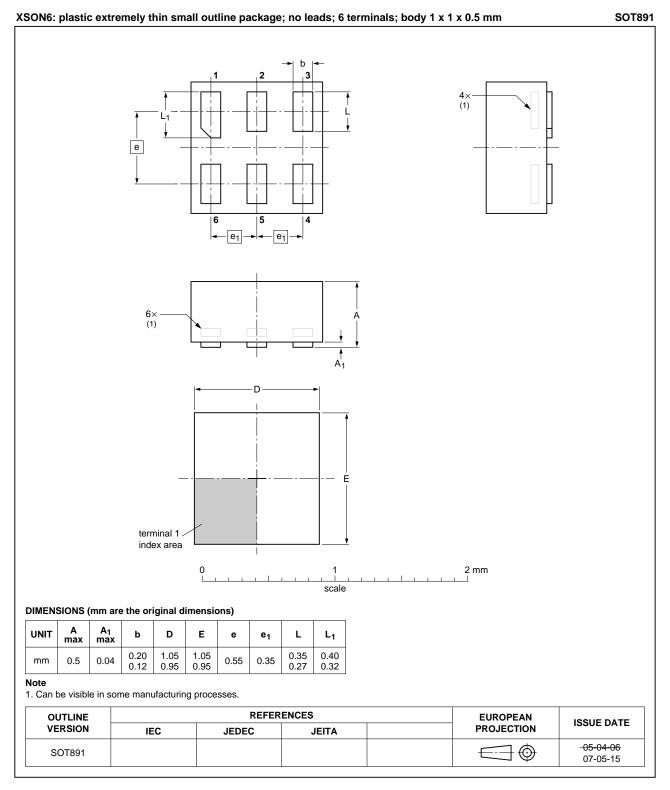
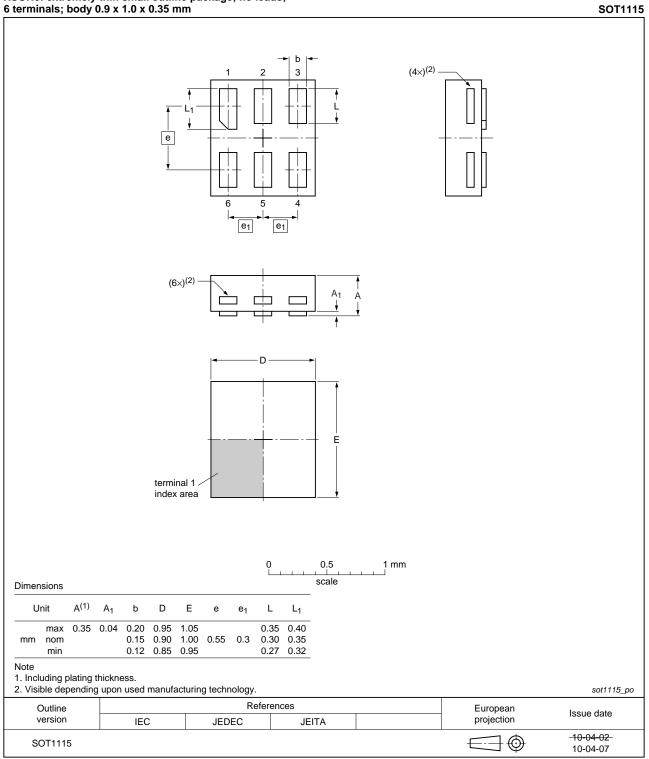


Fig 17. Package outline SOT891 (XSON6)

74AUP1Z04 Product data sheet

22 of 28

Low-power X-tal driver with enable and internal resistor



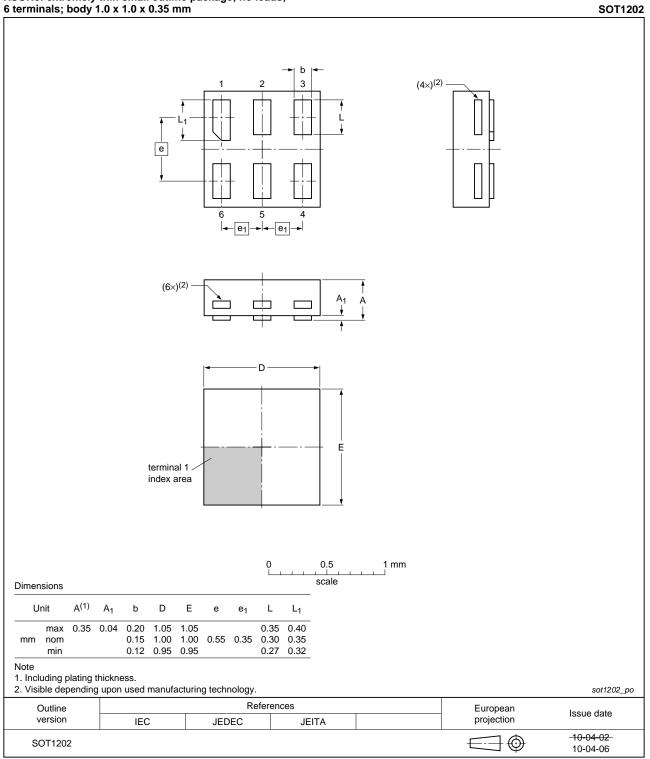
XSON6: extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm

Fig 18. Package outline SOT1115 (XSON6)

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74AUP1Z04

Low-power X-tal driver with enable and internal resistor



XSON6: extremely thin small outline package; no leads; 6 terminals; body 1.0 x 1.0 x 0.35 mm

Fig 19. Package outline SOT1202 (XSON6)

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74AUP1Z04

Low-power X-tal driver with enable and internal resistor

15. Abbreviations

reviations	
Description	
Charged Device Model	
Device Under Test	
ElectroStatic Discharge	
Human Body Model	
Machine Model	
	Description Charged Device Model Device Under Test ElectroStatic Discharge Human Body Model

16. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AUP1Z04 v.5	20120809	Product data sheet	-	74AUP1Z04 v.4
Modifications:	 Package ou 	tline drawing of SOT886 (Figure 16) modified.	
74AUP1Z04 v.4	20111201	Product data sheet	-	74AUP1Z04 v.3
Modifications:	 Legal pages 	s updated.		
74AUP1Z04 v.3	20100722	Product data sheet	-	74AUP1Z04 v.2
74AUP1Z04 v.2	20080703	Product data sheet	-	74AUP1Z04 v.1
74AUP1Z04 v.1	20061212	Product data sheet	-	-

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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[2] The term 'short data sheet' is explained in section "Definitions".

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74AUP1Z04

Low-power X-tal driver with enable and internal resistor

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Low-power X-tal driver with enable and internal resistor

19. Contents

1	General description	1
2	Features and benefits	1
3	Ordering information	2
4	Marking	2
5	Functional diagram	2
6	Pinning information	3
6.1	Pinning	3
6.2	Pin description	3
7	Functional description	3
8	Limiting values	4
9	Recommended operating conditions	4
10	Static characteristics	5
11	Dynamic characteristics 1	2
12	Waveforms 1	
13	Application information 1	7
13.1	Crystal characteristics 1	7
13.1.1		8
13.1.2		9
14	Package outline 2	0
15	Abbreviations 2	5
16	Revision history 2	
17	Legal information 2	6
17.1	Data sheet status 2	-
17.2	Definitions 2	
17.3	Disclaimers	-
17.4	Trademarks	
18	Contact information 2	
19	Contents 2	8

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